#### D. C. MOTORS

## PART V: THE SERIES MOTOR

# OBJECTIVES

# student will:

current is doubled.

experiments.

- Draw the necessary connections between given symbothat will complete a schematic diagram of a series motor circuit.
- Select, from a list of statements, the reason why series motors are widely used.
  - Complete a statement about the factor that limits armature current in a series motor which is supplied with a constant applied voltage.
- Select, from a list of statements, the reason why a series motor must always be connected to a load.

  Select, from a list of statements, the relationshi between torque and armature current in a series

motor, and the effect on torque when armature

- Complete a chart showing the effects caused by a change of load on a series motor.

  Complete a statement that identifies the series
- motor generally used in D. C. actuators.

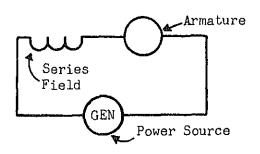
  Draw the necessary connections between given symbol
- that will complete a schematic diagram of a splitfield series motor.

  Draw the connections necessary to complete a diagr
  of a lab machine that may be used for series motor

RECOMMENDED READING TIME 45 MINUTES

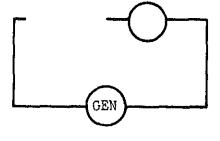
1.	The field coils, consisting of a
	few turns of heavy wire, are con-
	nected in series with a rotating
	ermature through a set of carbon
	brushes.
	The field coils of a series motor are
	made of a turns of heavy
	wire connected in series with the
	through a set of carbon
	·
2.	The series field is represented on a
	ind realist libration on a
	schematic diagram by the symbol ,
	·
	schematic diagram by the symbol ,
	schematic diagram by the symbol , which is connected in series with the
	schematic diagram by the symbol , which is connected in series with the armature, commutator, and brushes, rep-
	schematic diagram by the symbol, which is connected in series with the armature, commutator, and brushes, represented by the symbol The power source that will be used throughout this program is a generator, rep-
	schematic diagram by the symbol, which is connected in series with the armature, commutator, and brushes, represented by the symbol The power source that will be used through-
	schematic diagram by the symbol, which is connected in series with the armature, commutator, and brushes, represented by the symbol The power source that will be used throughout this program is a generator, rep-
	schematic diagram by the symbol, which is connected in series with the armature, commutator, and brushes, represented by the symbol The power source that will be used throughout this program is a generator, represented by the symbol GEN.
	schematic diagram by the symbol, which is connected in series with the armature, commutator, and brushes, represented by the symbol The power source that will be used throughout this program is a generator, represented by the symbol GEN.  The symbol for the series field is
	schematic diagram by the symbol, which is connected in series with the armature, commutator, and brushes, rep- resented by the symbol The power source that will be used through- out this program is a generator, rep- resented by the symbol GEN.  The symbol for the series field is, which is connected

 The schematic diagram below shows the electrical connections of a series motor.



If power is applied to a motor, wired as shown above, it will operate as a

 Complete the schematic diagram of a series motor shown below by drawing the missing symbol.



The symbol required above is the symbol for the

	5. Complete the schematic diagram be
	by drawing the symbols for the po
GEN	source and the armature.
es field	
	6. The series motor field and armati
	6. The series motor field and armati
	windings must carry the full load
GEN CEN	
GEN GEN	windings must carry the full load

Draw the necessary connections be

the symbols below to complete a

schematic diagram of a series mod

GEN)

circuit.

7.

es

3

	8.	The series motor is widely used because it has HIGH STARTING TORQUE and rapid acceleration.  The motor widely used because of its high starting torque and acceleration is the motor.
	9.	An installation requiring a motor with high starting torque would use series motor.  The series motor is used in installations that require high
g torque	10.	Select, from the list of statements below, the reason that the series more is widely used. Circle the letter in front of the answer of your choice.  a. Series motors have good speed control and do not overheat.  b. Series motors have high starting cemf and constant speed.

torque and rapid acceleration.

ct   11. The heavy wire used in the construction
of both the field and armature windings
motor has very little resistance. Since there
few turns of this heavy wire in the field and
ndings, the internal resistance of the series
ry low. When voltage is applied to a series
low internal resistance will allow high current
h the field and armature windings. Before the
gins to turn, the only thing that will oppose
w is the low resistance of the field and armature
hus, current flow will be maximum at start.
ture begins to turn, a cemf is induced into the
ndings which opposes the applied voltage and,
opposes the current flow from the power source.
duced into the armature windings <u>ligits</u> the
w in a series motor.
motor has very internal resistance.
he current flow in a series motor will be
imum because there is no induced cemf to

5

the applied voltage.

w through a series motor that

tage is limited by the amount

o the armature windings.

m,oppose	applied voltage, the cemf induced	
	into the rotating armature will op	qc
	the E <sub>app</sub> and the current through t	:h
	field and armature windings will d	Зe
	crease. When the current through	t
	windings of a series motor decreas	3e
l	the flux field produced by this	
	current will decrease.	
	The cemf, induced into the rotating	ng
	armature windings, limits the amou	
	through the field a	
	armature windings.	~
	~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~ ~	-
t	The decrease in current flow throu	1g
	the field and armature windings,	
	caused by the induced cemf, will o	дe
	crease thefield.	
	13. In a series motor with a constant	
	applied voltage the current flow	
	through the field and armature	
	windings is limited by the amount	
	of	

12. In a series motor, with a constant

15.

8e

se

torque.

decreases when the armature begins turn because cemf induced causes th armature current to A decrease in the current flow thro

As the armature begins to turn, the

cemf induced into it causes the Ia

Torque developed by a series motor

to decrease, thus decreasing the

- the armature and field windings can field strength  $(\beta)$  to weaken and results in speed increasing. As the armature speed continues to increas
- cemf increases, and, as a result, the field strength weakens even more. The weakening field strength, as sp increases, gives the series motor

feature of rapid acceleration to the

A decrease in armature current cau

- point where it is producing only the torque required by the load.
- field strength to increase/decrease

7

Continue on next page.

	A decrease in field strength results
	in a speed <u>increase/decrease</u> . This. (circle one)
	in turn, causes cemf to increase and
	limit the current to
	the value needed to develop the torq
	required by the load.
se	A series motor accelerates rapidly
re	to the point where it is producing t
	required by the load.
	16. The series motor produces or develop
	the torque required by the load to
	which it is connected. The torque
	developed by a series motor is propo
	tional to armature current squared,
	$(I_a)^2$ . At the moment of start, torq
	is maximum because armature current
	at its maximum value.
	At start, maximum armature current
	in a series motor causes torque to
	be, because torque
	developed by a series motor is pro-
	portional to the
	squared.
**************************************	
<del></del>	8

a load attached, it wil	1 accelerate
rapidly. With no load	attached, the
only torque required is	that needed
to turn the armature.	The speed at
which cemf would be of	sufficient
value to control Ia is	in excess of
design speed. The rapi	id acceleration
of a series motor with	no load on it
will continue until the	e bearings
burn out, or the armate	
are thrown out of their	
destroying the motor. I	
A SERIES MOTOR MUST NE	····
WITHOUT A LOAD ATTACHED	D.
The torque produced by	a series motor
is proportional to	
current squared.	
If a series motor is s	tarted without a
load attached, it will	
rapidly to the point w	here it will
itself.	
A series motor may some	
never be started with	no load attached

17. If a series motor is started without

Ъe	18.	Select, from the list of statements below, the reason that a series motor must always be connected to a load. Circle the letter in front of the answer of your choice.  a. The series motor must always be
		connected to a load so that it will not build up excessive counterelectromotive force.
		<ul> <li>b. The series motor must always be connected to a load so that it will not build up excessive speed and destroy itself.</li> <li>c. The series motor must always be</li> </ul>
		connected to a load so that it will not build up an excessive amount of armature current.
ect.	19.	The torque developed in a series motor is proportional to the square of the armature current.  In a series motor, the torque developed is proportional to the

20.	A series motor, carrying 2 amperes of
	armature current, will develop a def-
	inite amount of torque to carry a
	load. If the load is increased to
	where it takes four times the original
	amount of torque to carry the load,
	the armature current would increase
	to only 4 amperes. The fact that
	torque in a series motor is propor-
	tional to $I_a^2$ enables a relatively
	small change in armature current to
	correct for large changes in load.
	Doubling the armature current in a
	series motor will result in the motor
	developing <u>four</u> <u>times</u> as much torque.
	Large changes in the load on a series
	motor will cause only

small change in

the torque developed will be

If the  $I_a$  of a series motor is doubled,

times the original value.

ure	21.	The torque developed by a series mo
		is to the square of
		armature current.
ortional	22.	The torque developed by a series mo
		will increase to four times the ori
	į	inal value if the armature current
		•
ed	23.	Select, from the list of statements
·	!	below, the relationship between tor
armature c	urrent	in a series motor and the effect or
s torque wh	en the	Ia is doubled. Circle the letter i
nt of the a	nswer (	of your choice.
Torque in	a serie	es motor is proportional to the squa
of the arm	ature o	current; thus, doubling the Ig would
cause an i	ncrease	e of four times the amount of torque
being deve	loped.	
Torque in a	a serie	es motor is proportional to the squa
		oltage; thus, doubling the $I_a$ would h
		amount of torque being developed.
		es motor is proportional to the arma
current div	vided b	by the applied voltage; thus, doublin
would doub!	le the	amount of torque being developed.

		motor will cause less cemf to be induced. When the cemf decreases and the applied voltage $(E_{app})$ is constanted the effective voltage $(E_{eff})$ will increase because $E_{eff} = E_{app} - cemf$ . With constant $E_{app}$ , a decrease in the speed of a series motor will cause cemf induced to and
		Eeff to
a se a se	27.	When the effective voltage increase the armature current will increase. Since the same current flows through the series field coil, the strength of the field $(\beta)$ must also increase An increase in $E_{eff}$ will cause $I_a$ the polynomial cause the strength of the series find $(\beta)$ to
	1	

26. A decrease in the speed of a series

14

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28.	Load, torque (T), effective voltage
	$(E_{eff})$ , armature current $(I_a)$ , and
	field strength in a series motor are
	all directly proportional. If the
	load on a series motor increases, T,
	$E_{ m eff},\ I_{ m a}$ , and $eta$ will all increase.
	A decrease of the load on a series
	motor being supplied with a constant
	$E_{app}$ will cause T, $E_{eff}$ , $I_a$ , and $\beta$ to
	because they are direct-
	ly proportional.

changes that occur within the series the load is increased or decreased. Notice, in selow, that the proportional items vary in the same The arrows up ( ) indicate an increase and the ( ), decrease.

29. A chart may be used to indicate the

-,			····				
	LOAD	SPEED	cemf	Eeff	Ia	β	T
nt	increa se	V	<b>\</b>	<b>A</b>	4	4	Ŷ
nt	DECREA SE	4	A	<b>*</b>	•	V	•
	<del></del>	<u> </u>					

load is decreased. Draw an arrow in the appropriate boxes, up ( ) to indicate increase and down ( ) to indicate decrease.

cemf

Eeff

 $I_a$ 

T

β

SPEED

LOVD

qqs

crease in the cemf induced. Complete the chart below

to show the effect on torque, speed, and  $I_a$  when the

onstant	DE CREA SE						
Your co	mpleted ch	art in i	Erame 30	shoul	d 100	k like	the
chart s	hown below	. If y	our char	t does	not a	agree	, mval
any cor	rections n	ecessar	y before	conti	nuing	with	thi

any corrections necessary before continuing with thi frame.  $E_{\rm app} = E_{\rm AD} = E_{\rm BED} = E_{\rm eff} = E_{\rm a} = E_{\rm$ 

	<u></u>									_
ON <b>ST</b> ANT	DEC	REA SE		<b>A</b>	•	i	ł		•	
								<u>-</u>	. <u>.</u>	
ntinue	this	frame	on	the	next	pa	ge•			

delegação de como como como como como como como com		Maria de la contraction de la		harden geralan and agenta de la comprese de la comp	and the state of the second state of the	THE RESERVE THE PARTY OF THE PA	on the production of the production	PMS-77 II DO F
(Contá.	) A	s load	decreas	ses, les	s torq	ue is	requ:	irε
As torq	ue d	ecreas	ses, spee	ed will	increa	se an	d cemi	E W
increas	e.	Since	E <sub>eff</sub> is	equal t	o E <sub>app</sub>	minu	s the	ce
the E <sub>ef</sub>	f Wi	ll dec	rease be	ecause o	f the	increa	ase in	1 0
<b>T</b> his de	crea	se i.n	E <sub>eff</sub> cau	ises arm	ature (	curre	nt (I <sub>é</sub>	)
decreas	e an	d, sir	nce I <sub>a</sub> al	lso flow	s thro	ugh tl	ne set	ie
field c	oils	, fiel	d streng	yth (β)	will o	decrea	ase.	
If the	1oad	lona	series	motor is	incre	a <b>se</b> d,	torq	ue
must			, whi	ch will	cause	the s	peed	an
cemf to	o			E <sub>eff wi</sub>	11			<b></b> ,
causing	g an	incre	ase in b	oţh	and _	······································		
ease		32.	Complet	e the c	hart be	elow	to sho	)W
ea 8 e	Ì		a chang	ge in th	e load	on a	serie	es
ease β			will af	fect T,	E <sub>eff</sub> ,	cemf	, I <sub>a</sub> ,	ar
		_	speed.	Draw a	rrows	in the	e appı	op
boxes,	up	( ) t	o indice	te incr	ease a	nd do	wn (	)
indica	te d	ecreas	e.				•	
								·
app	LC	ďΑ	SPEED	cemf	Eeff	I <sub>a</sub>	β	ı
CONSTANT	INCR	EA SE					A	
CONSTA NT	DECR	EA SE				•		l L
<del></del>	<u> </u>				erre en en departation per de militario (140			

chart shown below. If your chart does not agree w the chart below, return to frame 24 and redo the p gram from that point. T.OAD SPEED cemf

Your completed chart in frame 32 should look like

upp	ДСЛ			ett	La La	٦ _	
NSTA NT	INCREASE		· ·	1	A	P	
IN AT RN	DE CREA SE						
The p	rimary use	of the	series	motor	in av	iation	ıis

starters for aircraft engines. The series motor is

used because it is able to supply the high torque

Many actuators for such devices as bomb-bay doors,

necessary for engine starting.

which is easily reversed.

wing flaps is the

D. C. series motor.

cockpit canopies, and wing flaps also use a series motor. The series motor is used because these dev must start under full mechanical load. The motor erally used is the SPLIT-FIELD, D.C. SERIES motor,

such things as cockpit canopies, bomb-bay doors, a

18

The motor generally used in aircraft actuators for

35. The feature that makes the split-field series motor easily reversible is two separate sets of oppositely wound field coils.

Current flow through one coil will cause rotation in one direction, and when the current is switched to the other coil, the direction of rotation will reverse.

The split-field series motor is easily
because it is construc-
ted with two sets of oppositely wound
•

The split-field series motor is used

36.

Notice, in the schematic diagram at that, if the switch is moved from position to the other, polarity of flux field produced will reverse.

This will cause the direction of armature rotation to reverse.

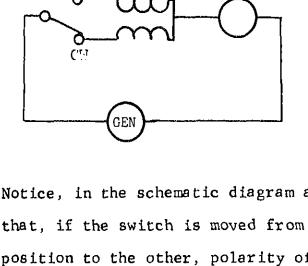
The two separate, oppositely wound

t-field

t-field

37.

38.



field coils give the split-field

motor the feature of being easily

The motor generally used in D. C.

The schematic diagram below shows

proper connection of a split-field

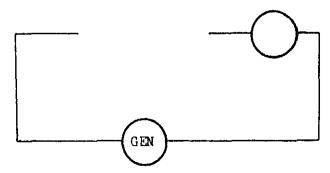
series motor.

actuators is the

series motor.

CCM

39. Draw the necessary symbols to complete the schematic diagram below to show the correct connection of a split-field series motor circuit.

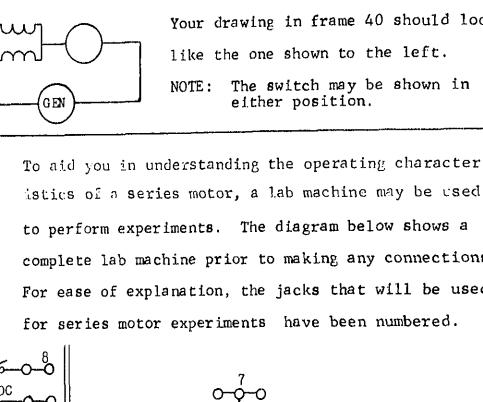


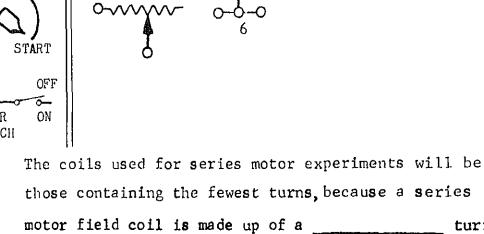
The major difference between the standard series motor and the split-field series motor is the two oppositely wound

40. Draw the necessary connections
between the symbols below that will
complete a schematic diagram of a
split-field series motor circuit.









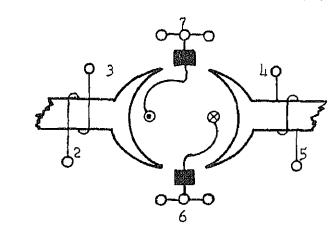
of wire.

TOR EED TROL 42. To make a clearer diagram, all parts unused in series motor experiments have been left off the diagram shown ll instructions carefully and use the

low all instructions carefully and use the

"to check the polarity of the connections and
on of rotation. Draw in lines to indicate the

connections. NOTE: Instructions are given below the drawing.



ut (jack No. 1) to the lower left field coil
o. 2) so the face of the left pole piece has
polarity.
jumper wire from the upper left field coil
o. 3) to the right field coil (jack No. 4) so the

jumper wire from the negative side of the 28-

the right pole piece has a south polarity.

jumper from the right field coil (jack No. 5) to
ative brush (jack No. 6) so as to give the motor
clockwise rotation.

jumper from the positive brush (jack No. 7) to itive side of the 28-VDC input (jack No. 8).

frame 42 should match the connections shown on the diagram below. NOTE ROTATION IS COUNTERCLOCKWI 3 Let's review a few points you have learned about th series motor. The series motor is widely used because it has a, rapid acceleration and high starting \_\_\_\_\_ Ъ. The series motor must always be connected to a so that it will not build up excessive

The connections you have just drawn on the diagram

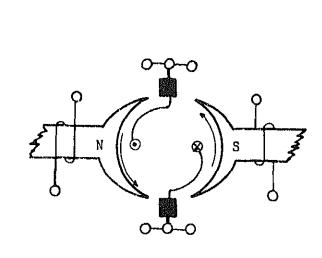
and destroy itself. Torque in a series motor is proportional to the С. square of the \_\_\_\_\_ current.

d. If the armature current in a series motor is do

the torque will increase to \_\_\_\_\_ time the original amount developed.

d. d. four

elete the diagram below to show a lab machine sected to perform series motor experiments. Draw the connections between the jacks necessary to lete the diagram and set up the magnetic polarities



'n.

to frame 43 to check the accuracy of your

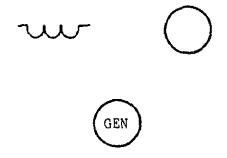
HAVE COMPLETED THE INSTRUCTIONAL PORTION OF PROGRAM; A SELF-TEST BEGINS ON THE NEXT PAGE.

## SELF-TEST

for

THE SERIES MOTOR

raw the necessary connections between the symbols elow that will complete a schematic diagram of a eries motor circuit.



high starting cemf.

select, from the list of statements below, the reaso that series motors are widely used. Circle the lett n front of the answer of your choice.

not subject to overheating. Series motors are constant-speed motors and have ٠,

Series motors have excellent speed control and a

- Series motors have high starting torque and .
- rapid acceleration.

The armature current flowing through a series mot that has a constant voltage applied is limited by amount of \_\_\_\_\_\_ induced into the armature

Select, from the list of statements below, the reason that a series motor must always be connected to a load. Circle the letter in front of the answer of your choice.

load so that when it is started, it will not build up excessive counterelectromotive force.

a.

The series motor must always be connected to a

- b. The series motor must always be connected to a load so that when it is started, it will not build up excessive speed and destroy itself.
- c. The series motor must always be connected to a load so that when it is started, it will not build up excessive armature current.

Select, from the list of statements below, the relationship between torque and armature current in a series motor and the effect on torque when the armature current is doubled. Circle the letter

in front of the answer of your choice.

- a. Torque in a series motor is proportional to
  the square of the armature current; thus, doublir
  the armature current would cause an increase of
  four times the amount of torque being developed.
- b. Torque in a series motor is proportional to the square of the applied voltage; thus, doubling the armature current would have no effect on the amount of torque being developed.
- e. Torque in a series motor is proportional to
  the armature current divided by the applied
  voltage; thus, doubling the armature current
  would double the amount of torque being developed

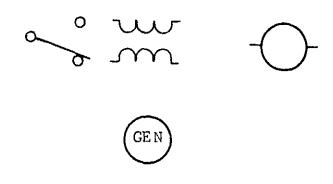
plete the chart below to show how a change in the d will affect torque, cemf, and I<sub>a</sub> of a series or. In the appropriate boxes, draw an arrow up to indicate increase or down ( ) to indicate rease.

	LOAD	SPEED	cemf	E <sub>eff</sub>	Ι <sub>a</sub>	β	T
A NT	INCREA SE	<b>\</b>		A		4	
A NT	DE CREASE	<b>A</b>		*		4	

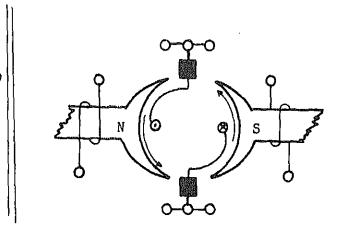
- \_\_\_\_\_ series motor.

motor generally used in D.C. actuators is the

w the necessary connections between the symbols ow that will complete a schematic diagram of a it-field series motor circuit.



Complete the diagram below to show a lab machine connected to perform series motor experiments. Draw the connections between the jacks necessary to complet the diagram and set up the magnetic polarities shown.



END OF TEST.